

The Pendulum as a SHO

To be a SHO, recall F must be proportional to $-x$

Consider a pendulum of length, l

x = horizontal disp. from equil.
 s = arc length from equil.

Recall
 $\sin \theta = \theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} - \frac{\theta^7}{7!} + \dots$
 θ small
 $\sin \theta \approx \theta$

Assume θ small

$$x \approx s = l\theta$$

← taking back to equil.

$$\Sigma F = F_{gs} = -mg \sin \theta$$

If θ small

$$\Sigma F \approx -mg\theta$$

$$\approx -mg \frac{x}{l}$$

$$F = -\frac{mg}{l} x$$

is of the form

$$F = -kx$$

$$\text{with } k = \frac{mg}{l}$$

Comparisons (Frequency and Period)

Pendulum

$$T = 2\pi \sqrt{\frac{m \cdot l}{mg}}$$

$$= 2\pi \sqrt{\frac{l}{g}}$$

$$f = \frac{1}{T} = \frac{1}{2\pi} \sqrt{\frac{g}{l}}$$

$$V_0 = \sqrt{\frac{mg \cdot l}{m}} A$$

$$V_0 = \sqrt{\frac{g}{l}} A$$

Spring

$$T = 2\pi \sqrt{\frac{m}{k}}$$

$$f = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

$$V_0 = \sqrt{\frac{k}{m}} A$$

Circle

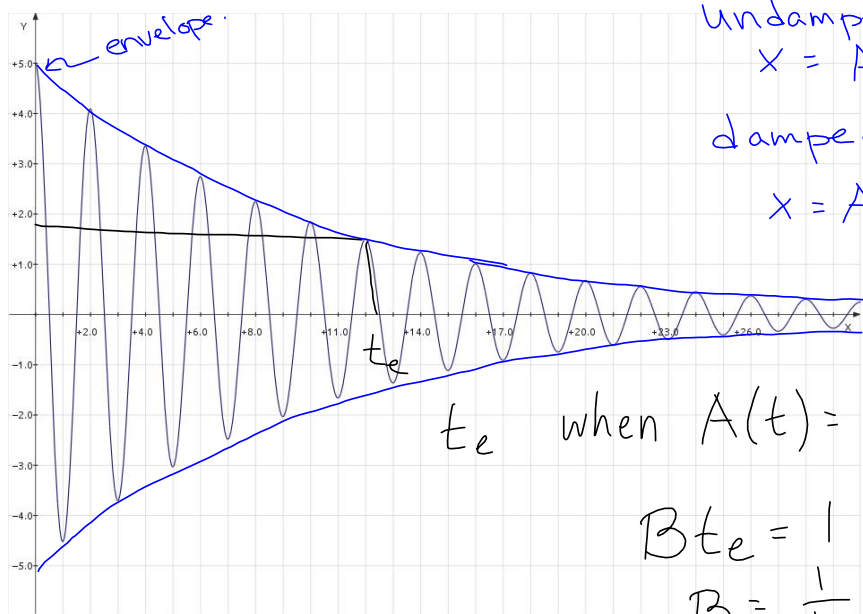
$$T = \frac{2\pi A}{V_0}$$

$$f = \frac{V_0}{2\pi A}$$

$$V_0 = \frac{2\pi A}{T}$$

$$V_0 = \sqrt{\frac{k}{m}} A$$

Real Life - Damped Harmonic Oscillators



undamped

$$x = A \cos 2\pi f t$$

damped

$$x = A e^{-Bt} \cos 2\pi f t$$

how quickly
it damps
depends on B

$$t_e \text{ when } A(t) = \frac{A(0)}{e}$$

$$B t_e = 1$$

$$B = \frac{1}{t_e}$$

A note on e

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \dots$$
$$\frac{de^x}{dx} = \text{☺} + 1 + \frac{2x}{2!} + \frac{3x^2}{3!} + \frac{4x^3}{4!} + \dots$$
$$= 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots = e^x$$

Quality factor of a spring

We define t_e to be the time for the amplitude of oscillation to drop to $1/e$ the initial amplitude.

$$A(t_e) = \frac{A(0)}{e} = \frac{A}{e}$$

$$A(t) = A_0 e^{-\frac{t}{t_e}}$$

Then the quality factor, Q , is given by

$$Q = 2\pi f t_e.$$

